## Fisher ${ }^{\circledR} 1078$ Declutchable Manual Actuator

Fisher 1078 manual actuators are declutchable actuators for manual operation of control valves and equipment that use power actuators. The 1078 manual actuator mounts directly to Fisher 1052 size $70 ; 1061$ sizes $30,40,60,68,80$, and 100 ; and to all sizes of 2052 actuators.

## Features

- Direct Attachment to the Power Actuator - Direct mounting to the actuator housing simplifies installation and eliminates the need for yokes and other brackets.
- Engage Manual Actuator At Any Point of Rotation A lever-operated eccentric bearing support on the input shaft allows engagement of the worm gear with the sector at any point of rotation. Because the travel indicator components are mounted on a through shaft, accurate travel indication is maintained during manual actuator disengagement or engagement.
- Positive Operation - The disengagement lever is locked in both the engaged and disengaged positions by a detent mechanism, which must be released before the lever can be moved. This provision reduces the possibility of inadvertent or accidental operation. In addition, stop-pins at the fully engaged and fully disengaged positions provide positive limits for lever travel. (Note that stop pins are not available on 1078 size II-FA actuators.)


FISHER 1078 DECLUTCHABLE MANUAL ACTUATOR MOUNTED ON A 2052 SIZE 1 ACTUATOR


FISHER 1078 DECLUTCHABLE MANUAL ACTUATOR MOUNTED ON A 2052 SIZE 1 ACTUATOR AND V300 VALVE WITH FIELDVUE ${ }^{\text {TM }}$ DVC6200 DIGITAL VALVE CONTROLLER

Table 1. Specifications

## Available Configurations

Direct and reverse acting; see Handwheel Rotation and the Ordering Information section, (Standard construction is with the handwheel shaft pointing down away from the power actuator as shown in the figure on page 1)

## Manual Actuator Sizes

See tables 1, 2, and 3
See figures 1 and 2 for dimensions

## Coupling Shaft Diameters

See tables 1, 2, and 3

## Power Actuator Compatibility

See tables 1, 2, and 3

## Maximum Torque Output

See tables 1, 2, and 3

## Wheel-Rim Force

See tables 1, 2, and 3

## Handwheel Rotation

Clockwise handwheel rotation closes the valve. Direct-acting units produce output rotation matching input rotation; reverse-acting units produce output rotation opposite input rotation.

## Construction Materials

Housing and Cover: Cast iron Drive Sleeve/Gear (Sector): Aluminum/bronze

Worm Gear: Heat-treated steel Input Shaft and Eccentric: Low-carbon steel Pin Detent: 300 Series stainless steel Handwheel or Input Shaft Bearings: Bronze

## Standard Mounting Positions

■ 1052 (size 70) ${ }^{(1)}$ : Handwheel down (std) or handwheel right-hand or left-hand mount (optional)

- 1061 (sizes $30,40,60,68,80$, and 100) ${ }^{(1) \text { : }}$

Handwheel down (std) or handwheel right-hand or left-hand mount (optional)
■ 2052 (sizes 1, 2, and 3) ${ }^{(1)}$ : Handwheel down (standard) or handwheel right-hand or left-hand mount (optional)

## Approximate Weight Without Handwheel

Size AAA: 2.7 kg ( 6 pounds)
Size AA: 6.8 kg ( 15 pounds)
Size A: 9.5 kg (21 pounds)
Size 2A: 13.6 kg ( 30 pounds)
Size 1A: 15.9 kg ( 35 pounds)
Size B: 23.1 kg ( 51 pounds)
Size C: 29.9 kg ( 66 pounds)
Size D: 63.5 kg ( 140 pounds)
Size II-FA: 81.6 kg ( 180 pounds)

## Handwheel Weight

6 -inch: 1.8 kg (4 pounds)
8 -inch: 2.3 kg ( 5 pounds)
12 -inch: 3.2 kg ( 7 pounds)
16-inch: 6.8 kg ( 15 pounds)
$24-\mathrm{inch}: 5.4 \mathrm{~kg}$ ( 12 pounds)
30 -inch: 6.4 kg ( 14 pounds)
36 -inch: 7.3 kg (16 pounds)

1. If a positioner is used, the right-hand or left-hand mounting option will be limited to the side away from the positioner.

Table 1. Fisher 2052 Actuator Size Selection and Specifications for Sizes AAA, A, and C

| MANUAL ACTUATOR SIZE | SHAFT SIZE |  | POWER ACTUATOR |  | STANDARD HANDWHEEL DIAMETER |  | MAXIMUM TORQUE |  | WHEEL-RIM-FORCE |  |  |  | HANDWHEEL <br> TURNS FOR <br> ROTATION <br> Degrees |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | For Maximum Torque | For Less Than Maximum Torque |  |  |  |  |  |
|  | mm | Inch |  |  | Type | Size | mm | Inch | N•m | Lbf•in | N | Pounds | N | Pounds | 60 | 90 |
| AAA <br> (2400 in •lbs) | 12.7 | 1/2 | 2052 | 1 |  |  | 203 | 8 | 131 | 1156 | 144 | 32 | Divide $\mathrm{N} \bullet \mathrm{m}$ req'd by 0.91 | Divide lbf•in req'd by 36 | 4 | 6 |
|  | $\begin{gathered} \hline 14.2 \times 15.9 \\ 15.9 \end{gathered}$ | $\begin{gathered} 9 / 16 \times 5 / 8 \\ 5 / 8 \end{gathered}$ |  |  | 211 | 1866 |  |  | 232 | 52 |  |  |  |  |
|  | 19.1 | 3/4 |  |  | 271 | 2400 |  |  | 298 | 67 |  |  |  |  |
| $\begin{gathered} \text { A } \\ (8000 \mathrm{in} \bullet \mathrm{lbs}) \end{gathered}$ | $\begin{gathered} 14.3 \times 15.9 \\ 15.9 \end{gathered}$ | $\begin{gathered} 9 / 16 \times 5 / 8 \\ 5 / 8 \end{gathered}$ | 2052 | 2 | 406 | 16 | 489 | 4326 | 204 | 45 | Divide $N \bullet m$ req'd by 2.4 | Divide lbf•in req'd by 96 | 5.3 | 8 |  |  |
|  | 19.1 | 3/4 |  |  |  |  | 590 | 5221 | 246 | 54 |  |  |  |  |  |  |
|  | 22.2 25.4 | $7 / 8$ 1 |  |  |  |  | 818 | 7241 | 341 | 75 |  |  |  |  |  |  |
|  | $\begin{array}{\|c\|} \hline 28.6 \times 31.8 \\ 31.8 \end{array}$ | $\begin{gathered} \hline 1-1 / 8 \times 1-1 / 4 \\ 1-1 / 4 \end{gathered}$ |  |  |  |  | 904 | 8000 | 377 | 83 |  |  |  |  |  |  |
|  | 19.1 | 3/4 | 2052 | 3 | 610 | 24 | 1338 | 11842 | 279 | 61 | Divide N•m req'd by 4.8 | Divide lbf•in req'd by 194 | 9 | 13.5 |  |  |
|  | $\begin{aligned} & \hline 22.2 \\ & 25.4 \end{aligned}$ | $7 / 8$ 1 |  |  |  |  | 1566 | 13862 | 326 | 71 |  |  |  |  |  |  |
| $\begin{gathered} \text { C } \\ (18000 \\ \text { in•lbs }) \end{gathered}$ | $\begin{array}{\|c\|} \hline 28.6 \times 31.8 \\ 31.8 \\ 38.1 \\ 39.7 \times 44.5 \\ 44.5 \\ 50.8 \end{array}$ | $\begin{array}{\|c} \hline 1-1 / 8 \times 1-1 / 4 \\ 1-1 / 4 \\ 1-1 / 2 \\ 1-9 / 16 \times 1-3 / 4 \\ 1-3 / 4 \\ 2 \end{array}$ |  |  |  |  | 2034 | 18000 | 424 | 93 |  |  |  |  |  |  |

Table 2. Fisher 1052 Actuator Size Selection and Specifications for Sizes 1A, B, and C

| MANUAL ACTUATOR SIZE (max output torque) | SHAFT SIZE |  | POWER ACTUATOR ${ }^{(1)}$ |  | STANDARD HANDWHEEL DIAMETER |  | MAXIMUM TORQUE ${ }^{(2)}$ |  | WHEEL-RIM-FORCE |  |  |  | HANDWHEEL TURNS FOR ROTATION |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | For Maximum Torque | For Less Than Maximum Torque |  | Degrees |  |
|  | mm | Inch |  |  | Type | Size |  |  | mm | Inch | $\mathrm{N} \cdot \mathrm{m}$ | Lbf•in | N | Pounds | N | Pounds | 60 | 90 |
| $\begin{gathered} 1 \mathrm{~A} \\ (8200 \mathrm{in} . \mathrm{lbs}) \end{gathered}$ | $\begin{aligned} & 31.8, \\ & 28.6 x \\ & 31 / 8 \\ & \hline \end{aligned}$ | $\begin{gathered} \hline-1 / 4, \\ 1-1 / 8 x \\ 1-1 / 4 \end{gathered}$ | 1052 | 70(3) |  |  | 610 | 24 | 929 | 8200 | 378 | 85 | Divide $\mathrm{N} \bullet \mathrm{m}$ req'd by 2.4 | Divide lbf•in req'd by 96 | 5.3 | 8 |
|  | $\begin{gathered} \hline 38.1 \\ 31.8 \mathrm{x} \\ 38.1 \\ \hline \end{gathered}$ | $\begin{gathered} 1-1 / 2, \\ 1-1 / 4 x \\ 1-1 / 2 \\ \hline \end{gathered}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | $\begin{gathered} \hline(44.4, \\ 50.8), \\ 39.7 \\ \times 44.5 \end{gathered}$ | $\begin{gathered} (1-3 / 4, \\ 2), \\ 1-9 / 16 \\ \times 1-3 / 4 \end{gathered}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\begin{gathered} \text { B } \\ (12,000 \text { in.lbs }) \end{gathered}$ | 31.8 | 3/4 | 1052 | 70 | 610 | 24 | 1356 | 12,000 | 369 | 83 | Divide N•m req'd by 3.6 | Divide lbf•in req'd by 144 | 6.7 | 10 |  |  |
|  |  | 7/8-1 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | 1-1/4 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | $\begin{gathered} \hline 38.1, \\ (44.4, \\ 50.8) \end{gathered}$ | $\begin{gathered} \hline 1-1 / 2, \\ (1-3 / 4, \\ 2) \end{gathered}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\begin{gathered} \text { C } \\ (18,000 \text { in.lbs }) \end{gathered}$ | 31.8 | 1-1/4 | 1052 | 70 | 610 | 24 | 1735 | 15,355 | 361 | 79 | Divide $N \bullet m$ req'd by 4.8 | Divide lbf•in req'd by 194 | 9 | 13.5 |  |  |
|  |  |  |  |  |  |  | 1839 | 16,275 | 383 | 84 |  |  |  |  |  |  |
|  |  |  |  |  |  |  | 2034 | 18,000 | 414 | 93 |  |  |  |  |  |  |
|  | $\begin{gathered} (44.4, \\ 50.8) \end{gathered}$ | $\begin{gathered} (1-3 / 4, \\ 2) \end{gathered}$ |  |  |  |  | 2034 | 18,000 | 414 | 93 |  |  |  |  |  |  |
| 1. Field conversion of actuators for $F$ and $G$ mounting adaptations requires installation of new parts. <br> 2. Compare table value with torque requirements of the valve plus the torque required to compress the power actuator spring (from Fisher Catalog 14). Note that dynamic torque of the valve may have a positive or negative effect on total torque required. <br> 3. If mounted on the 1052 size 70 , the travel is for only 60 Degrees. |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

Table 3. Fisher 1061 Actuator Size Selection and Specifications for Sizes 2A, 1A, B, C, D, and II-FA

| MANUAL ACTUATOR SIZE (max output torque) | SHAFT SIZE |  | POWER ACTUATOR |  | STANDARD HANDWHEEL DIAMETER |  | MAXIMUM TORQUE(1) |  | WHEEL-RIM-FORCE |  |  |  | HANDWHEEL TURNS FOR ROTATION |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | For Maximum Torque | For Less Than Maximum Torque |  | Degrees |  |
|  | mm | Inch |  |  | Type | Size |  |  | mm | Inch | N•m | Lbf•in | N | Pounds | N | Pounds | 60 | 90 |
| $\begin{gathered} 2 \mathrm{~A} \\ (4800 \text { in.lbs) } \end{gathered}$ | 12.7 | 1/2 | 1061 | 30 |  |  | 152 | 6 | 58 | 515 | 89 | 20 | Divide <br> $N \bullet m$ req'd by 0.66 | Divide lbf•in req'd by 26 | 5.7 | 8.5 |
|  | $\begin{gathered} 15.9 \\ 14.3 \mathrm{x} \\ 9.5 \end{gathered}$ | $\begin{gathered} \hline 5 / 8, \\ 9 / 16 x \\ 5 / 8 \\ \hline \end{gathered}$ |  |  | 138 | 1225 |  |  | 214 | 48 |  |  |  |  |
|  | 19.1 | $3 / 4{ }^{(3)}$ |  |  | 203 | 8 | 239 | 2120 | 276 | 62 | Divide N•m req'd by 0.86 | Divide Ibf•in req'd by 34 |  |  |  |  |
|  | $\begin{aligned} & (22.2, \\ & 25.4) \end{aligned}$ | (7/8,1) |  |  | 305 | 12 | 467(4) | 4140 ${ }^{(4)}$ | 360 | 81 | Divide $N \bullet m$ req'd by 1.3 | Divide Ibf•in req'd by 51 |  |  |  |  |
|  | 31.8 | 1-1/4 |  |  |  |  | 541 | 4800 | 416 | 94 |  |  |  |  |  |  |
| $\begin{gathered} 1 \mathrm{~A} \\ \text { (8200 in.lbs) } \end{gathered}$ | 19.1 | 3/4 | 1061 | 40, | 305 | 12 | 239 | 2120 | 276 | 62 | Divide N•m req'd by 1.2 | Divide lbf•in req'd by 48 | 5.3 | 8 |  |  |
|  | $\begin{aligned} & \hline(22.2, \\ & 25.4) \end{aligned}$ | (7/8,1) | 1061 | $\begin{aligned} & 60 \\ & 68 \end{aligned}$ |  |  | 467 | 4140 | 382 | 86 |  |  |  |  |  |  |
|  | $\begin{gathered} \hline 31.8, \\ 28.6 x \\ 31 / 8 \\ \hline \end{gathered}$ | $\begin{gathered} \hline 1-1 / 4, \\ 1-1 / 8 x \\ 1-1 / 4 \end{gathered}$ | 1061 | $\begin{aligned} & 40, \\ & 60, \\ & 68 \end{aligned}$ | 610 | 24 | 929 | 8200 | 378 | 85 | Divide N•m req'd by 2.4 | Divide lbf•in req'd by 96 | 5.3 | 8 |  |  |
|  | $\begin{gathered} \hline 38.1 \\ 31.8 \mathrm{x} \\ 38.1 \\ \hline \end{gathered}$ | $\begin{gathered} \hline 1-1 / 2, \\ 1-1 / 4 x \\ 1-1 / 2 \end{gathered}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | $\begin{gathered} (44.4, \\ 50.8), \\ 39.7 \\ \times 44.5 \end{gathered}$ | $\begin{gathered} \hline(1-3 / 4, \\ 2), \\ 1-9 / 16 \\ x 1-3 / 4 \end{gathered}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\begin{gathered} \text { B } \\ (12,000 \\ \text { in.lbs }) \end{gathered}$ | 19.1 | 3/4 | 1061 | $\begin{aligned} & 40 \\ & 60, \\ & 68 \end{aligned}$ | 610 | 24 | 239 | 2120 | 66 | 15 | Divide $N \bullet m$ req'd by 3.6 | Divide lbf•in req'd by 144 | 6.7 | 10 |  |  |
|  | $\begin{aligned} & 22.2, \\ & 25.4 \end{aligned}$ | 7/8,1 |  |  |  |  | 468 | 4140 | 130 | 29 |  |  |  |  |  |  |
|  | 31.8 | 1-1/4 |  |  |  |  | 1109 | 9815 | 308 | 68 |  |  |  |  |  |  |
|  | $\begin{gathered} \hline 38.1, \\ (44.4, \\ 50.8) \end{gathered}$ | $\begin{gathered} \hline 1-1 / 2, \\ (1-3 / 4, \\ 2) \end{gathered}$ |  |  |  |  | 1356 | 12,000 | 377 | 83 |  |  |  |  |  |  |
|  | 31.8 | 1-1/4 | 1061 | $\begin{aligned} & 40, \\ & 60, \\ & 68 \end{aligned}$ | 610 | 24 | 1109 | 9815 | 231 | 51 | Divide $N \bullet m$ req'd by 4.8 | Divide Ibf•in req'd by 194 | 9 | 13.5 |  |  |
|  | $\begin{gathered} \hline(44.4, \\ 50.8) \end{gathered}$ | $\begin{gathered} (1-3 / 4, \\ 2) \end{gathered}$ |  |  |  |  | 2034 | 18,000 | 424 | 93 |  |  |  |  |  |  |
| $\begin{gathered} \text { D } \\ (30,000 \\ \text { in.lbs }) \end{gathered}$ | $\begin{gathered} (44.4, \\ 50.8) \end{gathered}$ | $\begin{gathered} (1-3 / 4, \\ 2) \end{gathered}$ | 1061 | $\begin{aligned} & 80 \\ & 100 \end{aligned}$ | 762 | 30 | 2658 | 23,524 | 369 | 82 | $\begin{gathered} \text { Divide } \\ \mathrm{N} \bullet \mathrm{~m} \text { req'd } \\ \text { by } 7.2 \end{gathered}$ | Divide Ibf•in req'd by 287 | 10.7 | 16 |  |  |
|  | $\begin{gathered} 54, \\ 63.5 \\ 57.2 x \\ 63.5 \end{gathered}$ | $\begin{gathered} 2-1 / 8, \\ 2-1 / 2, \\ 2-1 / 4 x \\ 2-1 / 2 \end{gathered}$ |  |  | 914 | 36 | 3390 | 30,000 | 394 | 87 | Divide $N \bullet m$ req'd by 8.6 | Divide Ibf•in req'd by 345 |  |  |  |  |
|  | $\begin{gathered} \hline 76 x \\ 63.5, \\ 101.6 x \\ 63.5 \end{gathered}$ | $\begin{gathered} 3 \times 2 \\ 1 / 2,4 x \\ 21 / 2 \end{gathered}$ | 1061 |  |  |  |  |  |  |  |  |  |  |  |  |  |
| II-FA ${ }^{(2)}$ (60,000 in.lbs) | $\begin{gathered} \hline 76 x \\ 63.5, \\ 101.6 x \\ 63.5 \end{gathered}$ | $\begin{gathered} 3 \times 2 \\ 1 / 2,4 x \\ 21 / 2 \end{gathered}$ | 1061 | $\begin{aligned} & 80 \\ & 100 \end{aligned}$ | 406 | 16 | 6301 | 55,762 | 400 | 90 | Divide N•m req'd by 15.7 | Divide Ibf•in req'd by 619 | 48 | 72 |  |  |
| 1. Compare table value with torque requirements of the valve (from Fisher Catalog 14). Note that dynamic torque of the valve may have a positive or negative effect on total torque required. 2. Has spur gear. <br> 3. 2A 3/4 inch shaft will also mount on the 1061 size 40,60 , and 68 . <br> 4. Maximum torque of connection between power and manual actuator. |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

Table 4. Dimensions for Actuator Sizes AAA, AA, and A

| 1078 Size | A | B | C | D | E | F | G | H | J | Square Bolt Pattern | Circular Bolt Pattern |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| mm |  |  |  |  |  |  |  |  |  |  |  |
| AAA | 305 | 184 | 40 | 67 | 178 | 204 | 106 | 46 | 51 | 57.1 SQ | --- |
| AA | 305 | 203 | 56 | 70 | 181 | 216 | 94 | 59 | 64 | 76.2 SQ | --- |
| A | 610 | 381 | 68 | 83 | 337 | 378 | 238 | 67 | 73 | 88.9 SQ | --- |
| Inches |  |  |  |  |  |  |  |  |  |  |  |
| AAA | 12.00 | 7.25 | 1.56 | 2.62 | 7.00 | 8.02 | 4.18 | 1.82 | 2.02 | 2.25 SQ | --- |
| AA | 12.00 | 8.00 | 2.19 | 2.75 | 7.12 | 8.50 | 3.69 | 2.31 | 2.50 | 3.00 SQ | --- |
| A | 24.00 | 15.00 | 2.69 | 3.25 | 13.25 | 14.88 | 9.38 | 2.63 | 2.88 | 3.50 SQ | --- |

Figure 1. Dimensions for Actuator Sizes AAA, AA, and A (also see table 4)

${ }_{\text {A5431-1 }}^{1182634-C}$

Note: This drawing is a typical view only. For some valves, the handwheel is on the opposite side.

Table 5. Dimensions for Actuator Sizes 2A, 1A, B, C, D, and II-FA

| $1078$ Size | A | B | C | D | E | F | G | H | J |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| mm |  |  |  |  |  |  |  |  |  |
|  | 152 | 230 | 55.4 | 116 | 155 | 140 | 17.5 | 58.7 | 63.5 |
| 2A | 203 |  |  |  | 181 | 165 | 42.9 |  |  |
|  | 305 |  |  |  | 232 | 216 | 93.7 |  |  |
|  | 305 |  |  |  | 235 | 229 | 82.6 | 69.9 | 76.2 |
| 1A | 610 | 229 | 68.3 | 124 | 387 | 381 | 235 |  |  |
|  | 203 | 229 | 84.1 | 140 | 194 | 191 | 19.1 | 82.6 | 88.9 |
| B | 305 |  |  |  | 244 | 241 | 69.9 |  |  |
|  | 610 |  |  |  | 397 | 394 | 222 |  |  |
| C | 610 | 254 | 102 | 149 | 400 | 416 | 200 | 105 | 111 |
|  | 762 | 254 | 117 | 203 | 505 | 506 | 262 | 119 | 125 |
| D | $914$ |  |  |  | $581$ | $583$ | $338$ |  |  |
| II-FA | 406 | 356 | 117 | 203 | 337 | 328 | 84 | 119 | 125 |
| Inches |  |  |  |  |  |  |  |  |  |
| 2A | 6.00 | 8.00 | 2.18 | 4.56 | 6.12 | 5.5 | 0.69 | 2.31 | 2.50 |
|  | 8.00 |  |  |  | 7.12 | 6.5 | 1.69 |  |  |
|  | 12.00 |  |  |  | 9.12 | 8.5 | 3.69 |  |  |
|  | 12.00 | 9.00 | 2.69 | 4.88 | 9.25 | 9.00 | 3.25 | 2.75 | 3.00 |
| 1A | $24.00$ |  |  |  | $15.25$ | $15.00$ | $9.25$ |  |  |
|  | 8.00 | 9.00 | 3.31 | 5.50 | 7.62 | 7.50 | 0.75 | 3.25 | 3.50 |
| B | 12.00 |  |  |  | 9.62 | 9.50 | 2.75 |  |  |
|  | 24.00 |  |  |  | 15.62 | 15.50 | 8.75 |  |  |
| C | 24.00 | 10.00 | 4.00 | 5.88 | 15.75 | 16.38 | 7.88 | 4.12 | 4.38 |
|  | 30.00 | 10.00 | 4.62 | 8.00 | 20.25 | 19.94 | 10.31 | 4.69 | 4.94 |
| D | 36.00 |  |  |  |  | 22.94 | 13.31 |  |  |
| II-FA | 16.00 | 14.00 | 4.62 | 8.00 | 13.25 | 12.94 | 3.31 | 4.69 | 4.94 |

Figure 2. Dimensions for Actuator Sizes 2A, 1A, B, C, D, and II-FA (also see table 5)


SIZES 2A, 1A, B, C, D


## Ordering Information

Whenever a power actuator is ordered with a 1078 manual actuator, all components are configured and mounted according to specifications of the order.

## Size AAA, AA, and A

Field installation of the 1078 onto existing actuators with F or G mounting adaptations requires installation of new power actuator parts. (The F and G mounting adaptations are the mounting methods normally used to mount 1052 and 2052 (size 1 and 2) actuators on Fisher valves.) Installation of a valve to bypass cylinder or diaphragm pressure during manual operation is also recommended.

## Size 2A, 1A, B, C, D, and II-FA

Field installation of the 1078 onto the following existing actuators with F or G mounting adaptations [1052 (size 70), 2052 (size 3), and 1061 (sizes 30, 40, $60,68,80$, and 100)] requires additional parts in most cases. Remove the cover and hub and then replace with the 1078 actuator. Most assemblies require a new lever and splined adaptor.

Table 6. Handwheel/Valve Shaft Rotation

| VALVE | 1078 ACTUATOR ACTION |  |  |
| :---: | :---: | :---: | :---: |
|  | Actuator Mounting |  |  |
|  | Right-Hand | Left-Hand | Left-Hand <br> (Optional)(3) |
| 8510, 8532, <br> 8580, 8590, <br> and 9500 | Direct Acting(1) | Direct Acting | NA |
| V150, V200, <br> and V300 | Reverse <br> Acting (2) | Reverse Acting | Direct Acting |
| V250 |  | Reverse Acting | Direct Acting |
| V500 and <br> CV500 | Reverse Acting | Reverse Acting | NA |
| 1. Direct acting is when the clockwise handwheel rotation produces clockwise valve <br> shaft rotation to close the avlev. <br> 2. Reverse acting is when the clockwise handwheel rotation produces counter <br> clockwise avile shaft rotation to close the valve. <br> 3. Aleft thand ball will be required for the NPS 3 through 12 series B and the NPS 14 <br> through 20, with or without an attenuator. |  |  |  |

When ordering, specify:

1. Power actuator type and size, and valve shaft size.
2. Right or left hand mounting and desired mounting position.
3. Direct or reverse acting manual actuator construction. Refer to the mounting positions shown in the appropriate actuator bulletin and order according to the guidelines in table 6.
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